

Expectation

Definition

For a discrete function $E[X]$ is defined as $\sum_{i=1}^{i=n} x_i p_i$

For a continuous function

$$E[X] = \int_{-\infty}^{+\infty} x f(x) dx$$

It is the generalised weighted mean function.

Hence $E[X] = \mu$

The following relationships hold

$$E[X + Y] = E[X] + E[Y]$$

$$E[aX] = a E[X]$$

if $E[X] = 0$ then $X = 0$

if $X = Y$ then $E[X] = E[Y]$

if $X = k$ then $E[X] = k$

If X and Y are independent then

$$E[XY] = E[X] \times E[Y]$$

Variance

$$\begin{aligned} \text{Var}[X] &= E[(X - E[X])^2] \\ &= E[X^2 - 2XE[X] + E[X]^2] \\ &= E[X^2] - 2E[X]^2 + E[X]^2 \\ &= E[X^2] - E[X]^2 \end{aligned}$$

Minimum Value

We can choose any reference point instead of $E[X]$ say k .

$$\begin{aligned} \text{Var}[X] &= E[(X - k)^2] \\ &= E[X^2 - 2kX + k^2] \\ &= E[X^2] - 2kE[X] + E[k^2] \\ &= E[k^2] - 2kE[X] + E[X^2] \end{aligned}$$

Now let

$$A \Rightarrow E[k^2] - 2kE[X] \text{ and}$$

$$B \Rightarrow E[X^2]$$

Introduce the term $E[X]^2$ to each.

$$A \Rightarrow E[k^2] - 2kE[X] + E[X]^2$$

$$B \Rightarrow E[X^2] - E[X]^2$$

Now we can factorise A to

$$A \Rightarrow E[(k - E[X])^2]$$

A is 0 when $k = E[X]$

ie $k = \mu$

and we are left with $E[X^2] - E[X]^2$ as before.

Hence the value of $\text{Var}[X]$ is a minimum when $k = E[X]$.

Consequences

When we take a sample we use $\bar{X}$ as our best estimate of μ .

However this is unlikely to be exact and so our initial estimate of the variance is biased – it is at the idealised minimum.

Strictly we are “missing” one degree of freedom for the calculation of $\bar{X}$.

The rule is

“whenever we use $\bar{X}$ as an estimate of μ we must divide by $n-1$ instead of n ”.

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